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Part III: Effective Complexity of Deep Learning Models

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Outline

Introduction

- Measure of Effective Model Complexity
- High Capacity Low Reality Phenomenon
- Discussion

Effective Model Complexity reflects the complexity of the function represented by deep models with <u>specific</u> parameterizations



If we informally regard a deep learning model as a "container".

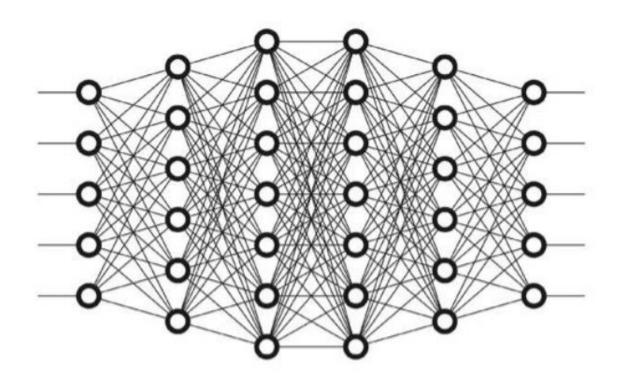
- Model framework
- Model size
- Optimization process
- Data complexity

• Model framework

- Model type? FCNN, CNN, RNN, ResNet ...
- Activation function? Tanh, ReLU ...
- Model size

• ...

- Number of hidden layers = ?
- Width of each layer = ?
- Number of filters = ?
- Number of trainable parameters = ?



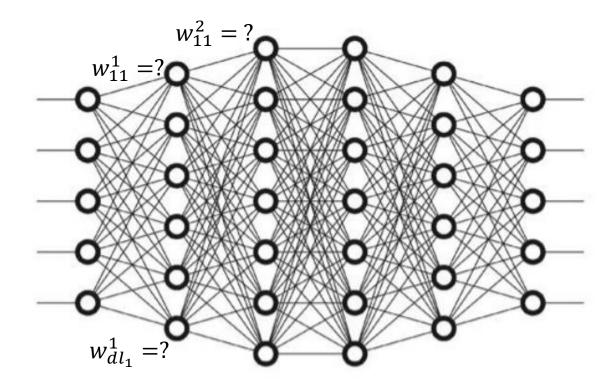
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• Optimization process

- What is the objective function?
- What is the optimization algorithm?
- The setting of hyper-parameters
- Data complexity

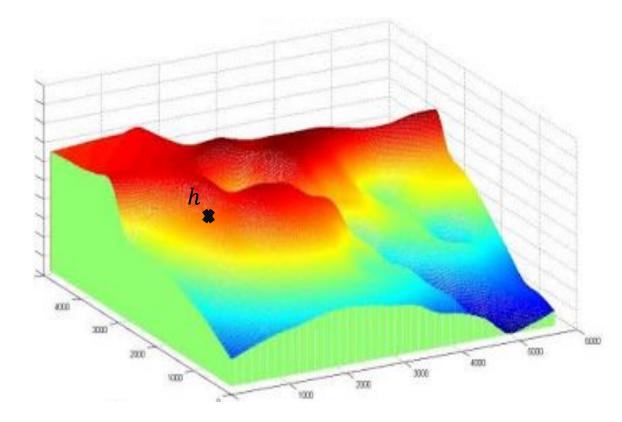
• ...

- Data dimensionality
- Number of class labels
- Data distribution



Reflected in the values of model parameters

- Model framework and size fixed
 - Model N
 - Corresponding hypothesis space *H*
- Model parameters fixed
 - A specific $h \in H$



Outline

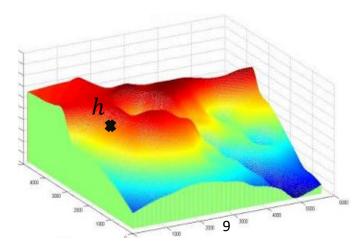
Introduction

Measure of Effective Model Complexity

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Measure of Effective Complexity

- Necessity to design quantitative measures for effective complexity of deep learning models.
 - Effective complexity cannot be directly derived from the model structure alone.
 - Different parameter values lead to different effective complexity.
 - Be sensitive to distinguish between models with the same structure but different parameter values.



What is the model complexity of h ?

• Piecewise linear property

- A finite number of linear regions
- Local linear model
- Deep neural networks with piecewise linear activation functions
 - ReLU
 - Hard Tanh
 - Maxout
 - ...

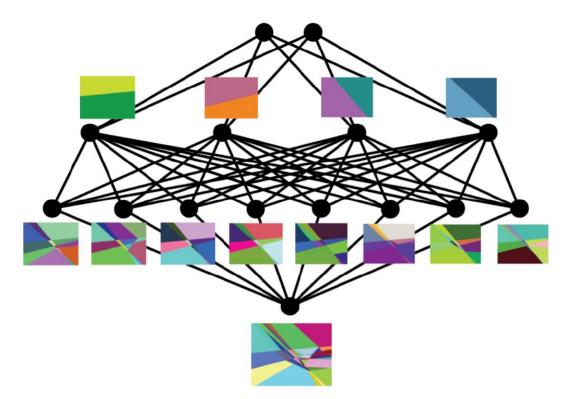


Figure from [Hanin and Rolnick, 2019]

• Trajectory path

 $x(t), t \in [0,1]$

 Number of linear regions through trajectory path

 $\Gamma(N(x(t);W))$

$$x_2 = x(1)$$
$$x_1 = x(0)$$

• Trajectory path

 $x(t), t \in [0,1]$

• Length of trajectory path

$$l(x(t)) = \int ||\frac{dx(t)}{t}||dt$$

$$x_2 = x(1)$$
$$x_1 = x(0)$$

• A deep ReLU neural network

$$E\left[l\left(z^{(i)}(x(t))\right)\right] \ge O\left(\frac{\sigma_w\sqrt{m}}{\sqrt{m+1}}\right)^i l(x(t))$$



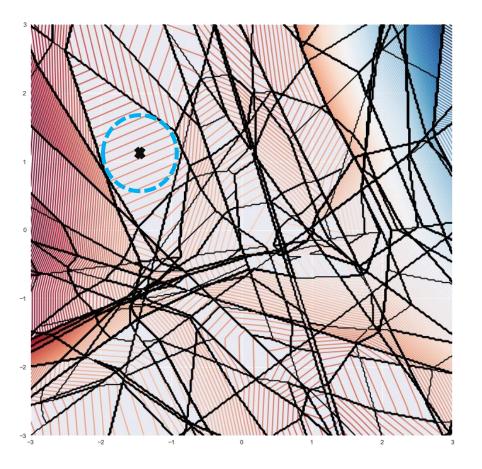
Figure from [Raghu et al., 2019] 13

[Raghu et al., 2017]

• Local sensitivity measure

 $E_{x\in D}[||J(x)||_F]$

 An input is perturbed within the same linear region

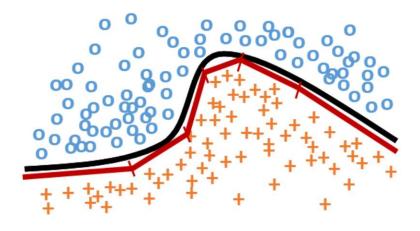


• The volume of boundaries between linear regions

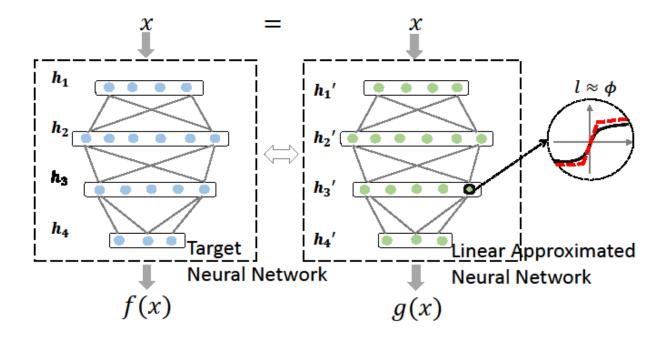
$$E\left[\frac{volume_{d-1}(B_N \cap K)}{volume_d(K)}\right] \approx T \cdot M$$

• Given a ReLU neural network $N: \mathbb{R}^d \to \mathbb{R}, d > 1$

- Deep neural networks with non-piecewise linear activation functions
 - Sigmoid, Tanh, ...
- Make them benefit from the piecewise linear property.



- Linear approximation neural network g(x)
 - Piecewise linear approximation with as small number of linear regions as possible



[Hu et al., 2020]

• Number of linear regions of the piecewise linear approximation

$$d\sum_{i} log \left(\sum_{j} k_{i,j} - m_i + 1\right)$$

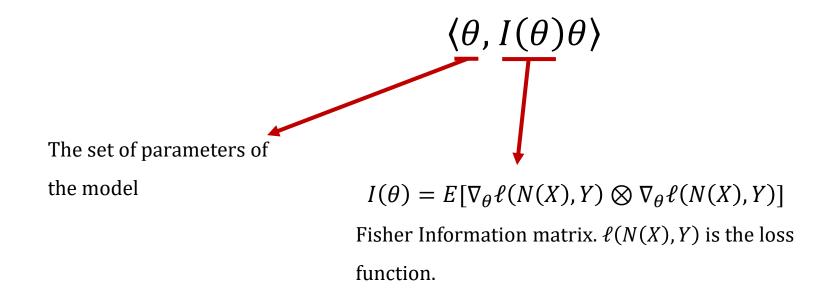
Other Measure Metrics

• Number of samples with non zero training error

 $\max\{n \mid E_{S \sim D} \left[Error_{S} (\Gamma(S)) \right] \leq \epsilon \}$

Other Measure Metrics

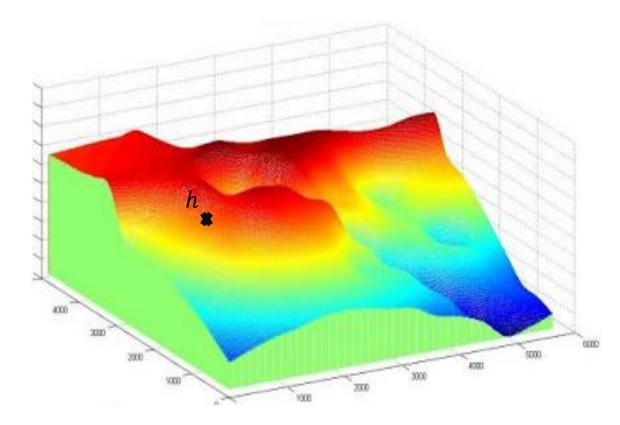
• Fisher-Rao Information



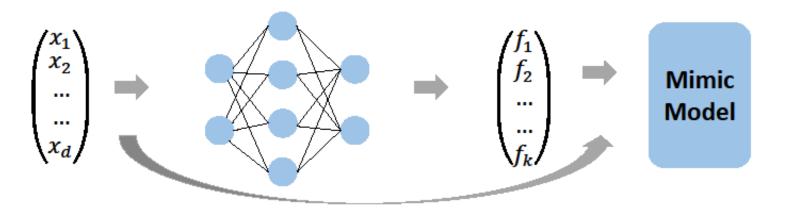
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- Expressive capacity is high
 - Deep learning models are always highly over-parameterized.
- Effective complexity of learned model is found to be low
- There might be a huge gap!



- Given a well-trained deep model
- A shallow model
 - Can mimic the deep model to as high accuracy as the deep one
 - Sometimes only requires the same number of parameters

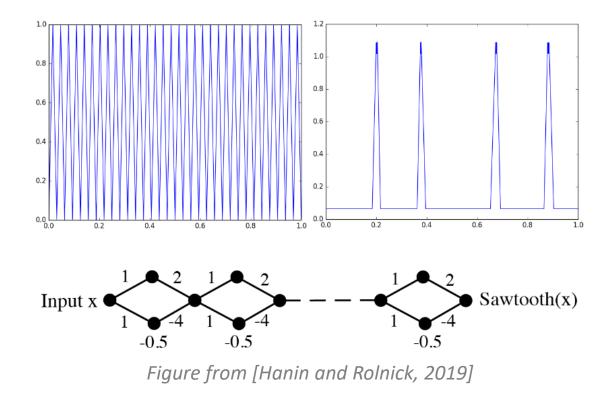


[Ba and Caruana, 2014]

- The effective complexity of the trained deep model might not be very high
 - It can be mimicked by a shallow one
- The strength of deep learning may arise in part from a good match between deep architecture and current training algorithms
 - Deep architectures might be easier to train by current optimization algorithms.

• Given a ReLU neural network $N: \mathbb{R} \to \mathbb{R}$

 $E[\#\{linear\ regions\ in\ S\}]\approx |S|\cdot T\cdot M$



[[]Hanin and Rolnick, 2019]

• Given a ReLU neural network $N: \mathbb{R}^d \to \mathbb{R}, d > 1$

$$E\left[\frac{volume_{d-1}(B_N \cap K)}{volume_d(K)}\right] \approx T \cdot M$$

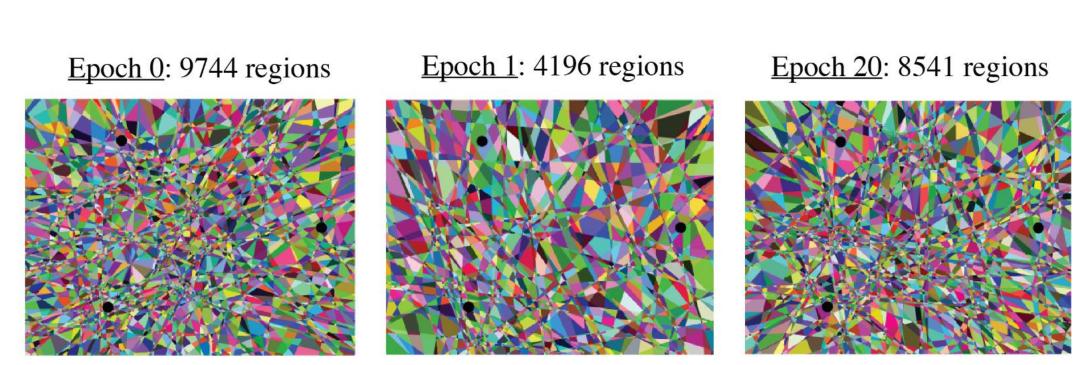


Figure from [Hanin and Rolnick, 2019]

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Discussion

- Effective model complexity is a relatively new, promising and useful problem in deep learning
 - Investigate the usefulness of optimization algorithms
 - Study the rule of regularizations
 - Develop new regularization approaches
 -

Discussion

- Other interesting problems
 - Cross-model comparison
 - Specify granularity of effective complexity measures